

BE1-R4: EMBEDDED SYSTEMS

NOTE:

1. Answer question 1 and any FOUR from questions 2 to 7.
2. Parts of the same question should be answered together and in the same sequence.

Time: 3 Hours

Total Marks: 100

1.
 - a) What are the typical characteristics of an embedded system?
 - b) Explain shared data problem.
 - c) Define VoIP.
 - d) Differentiate between Bluetooth and Zigbee.
 - e) Explain Task Control Block (TCB).
 - f) In what ways CISC and RISC processors differ?
 - g) What is "MICRO C/OS II"? What are the real time system level functions in "UC/OS II"?

(7x4)

2.
 - a) What is a device driver? Is it a software or a hardware? What are the generic and control functions of a device driver?
 - b) Explain the processors in an Embedded Systems.

(9+9)

3.
 - a) What are the various types of I/O ports? Briefly give their specific details with reference to 8051.
 - b) Name any two queue related functions for the inter task communications.

(10+8)

4. What I2C (Inter Integrated Circuit) SERIAL BUS COMMUNICATION PROTOCOL? What are its characteristics and standards? Also mention the disadvantages of the same.

(18)

5.
 - a) Explain priority inversion problem.
 - b) What is Watchdog timer? What is software timer? How are they different from each other?

(9+9)

6.
 - a) What are the various features of VxWorks? Name some application for the VxWorks RTOS. What are the basic functions of VxWorks?
 - b) Explain Controller Area Networks (CAN).
 - c) Give some examples of asynchronous communications used in embedded systems. Also give their characteristics of asynchronous communications and specific clock features.

(8+6+4)

7.
 - a) What is the distinction Between Function, ISR and Task in embedded systems with respect to uses, calling source and context saving?
 - b) What is Fragmentation Memory Allocation Problems in RTOS?

(10+8)